

# SANYO Semiconductors **DATA SHEET**

An ON Semiconductor Company

**LB1830M** 

# Monolithic Digital IC Low-Voltage, Low-Saturation Bidirectional Motor Driver

#### Overview

The LB1830M is a low-saturation bidirectional motor driver IC with brake function for use in low-voltage applications. As both of forward and reverse outputs are regulated, it is especially suited for use in portable equipment.

#### **Features**

- Wide operating voltage range: 3.0 to 9.0 V
- Low saturation voltage: 0.2V at  $I_O = 40mA$  (typ)
- Low current drain at standby mode (0.1µA or less)
- Brake function
- Regulated voltage value (forward/reverse) setting available by one variable resistor
- Regulated output/saturation output switching available
- Built-in spark killer diodes
- Small package: MFP10S

#### **Specifications**

**Absolute Maximum Ratings** at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
maximum supply voltage	V <sub>CC</sub> max		10.5	V
Output current	I <sub>M</sub> max		500	mA
Input supply voltage	VIN		-0.3 to +10	V
Allowable power dissipation	Pd max	Independent IC	0.4	W
		Mounted on a specified board *	0.55	W
Operating temperature	Topr		-20 to +80	°C
Storage temperature	Tstg		-40 to +125	°C

<sup>\*</sup> Specified board:  $30\text{mm} \times 30\text{mm} \times 1.5\text{mm}$ , glass epoxy board.

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#### SANYO Semiconductor Co., Ltd.

# **LB1830M**

# Allowable Operating Ranges at Ta = 25°C

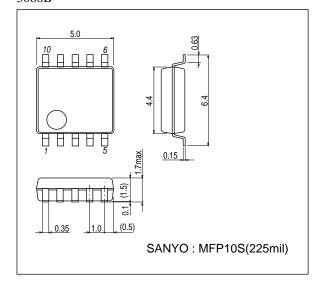
Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VCC		3.0 to 9.0	V
Input high level voltage	VIH		2.0 to 9.0	V
Input low level voltage	V <sub>IL</sub>		-0.3 to +0.3	V
Control voltage	VC		1.0 to 6.0	V

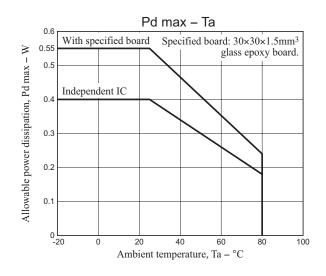
# **Electrical Characteristics** at Ta = 25°C, $V_{CC} = 6V$

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Parameter	Symbol	Conditions		typ	max	Unit	
Current drain	$I_{CC}$ 0 IN1 = IN2 = Vm = 0V, $V_C$ = Vref at standby mode			0.1	10	μА	
	I <sub>CC</sub> 1	Forward/reverse, control, load OPEN		2	3	mA	
	I <sub>CC</sub> 2	Forward/reverse, saturation, load OPEN		3	5	mA	
	I <sub>CC</sub> 3	Braking, load OPEN		5	8	mA	
Output saturation voltage	Vsat1	I <sub>O</sub> = 40mA (upper side + lower side)		0.2	0.3	V	
	Vsat2	I <sub>O</sub> = 80mA (upper side + lower side)		0.4	0.6	V	
Reference voltage	Vref	I <sub>Vref</sub> = 1mA	1.85	2.0	2.15	V	
Voltage characteristics of output voltage	$\frac{\Delta V_{O}}{\Delta V_{CC}}$	$V_O = 5V$ , $V_{CC} = 5.5$ to 9V, $I_O = 40$ mA			80	mA	
Current characteristics of output voltage	$\frac{\Delta V_{O}}{\Delta I_{O}}$	$V_O = 5V$ , $V_{CC} = 6V$ , $I_O = 10$ to 80mA			50	mA	
Input current	I <sub>IN</sub>	V <sub>IN</sub> = 5V		90	150	μА	
Output voltage	VO	V <sub>C</sub> = 2V	2.3×V <sub>C</sub>		2.5×V <sub>C</sub>	V	

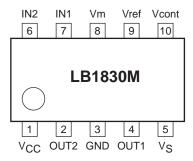
# **Package Dimensions**

unit : mm (typ) 3086B

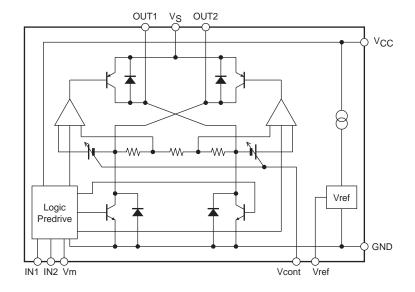




# **Pin Assignment**



# **Block Diagram**



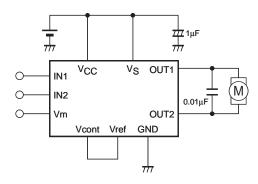
- The constant-voltage drive mode output voltage (the voltage between the output pins)  $V_O$  is determined by the following formula.  $V_O = (V_{CO} + V_{CO} + V_{CO$
- There are no restrictions on the relative magnitudes between the following voltages: V<sub>CC</sub> (control system supply voltage), VS (motor supply voltage), and IN1/IN2/Vm (the input signal voltages).

#### **Truth Table**

Input			Output		M
IN1	IN2	Vm	OUT1	OUT2	Mode
L	L	L	OFF	OFF	Standby
Н	L	L	Н	L	Forward (Regulated)
Н	L	Н	Н	L	Forward (Saturation)
L	Н	L	L	Н	Reverse (Regulated)
L	Н	Н	L	Н	Reverse (Saturation)
Н	Н	*	L	L	Brake

 $<sup>^{\</sup>star}$  when in saturation mode,  $V_{C}$  = VS available.

#### **Application Circuit Example**



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